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01. Preface

Thank you for choosing a REGNER® electric linear actuator. REGNER® actuators are high-tech products, carefully designed and manufactured in Europe. We use premium raw materials and we continue to work on developing better actuators to respond to the demands of our customers.

This manual will provide you with operational, maintenance and safety information about the actuator. We urge you to read this manual carefully and to follow its recommendations to make sure that the actuator is used properly and to its full potential.

The REGNER® team

02. Safety

Please read the following safety information carefully and make sure that everyone using, connecting or installing the actuator has the necessary skills and information, as well as access to this user manual.

02.01. Safety Guidelines

- Only properly qualified personnel can perform mechanical and electrical installation of the actuator.
- Do not mount, dismount or perform maintenance work while the actuator is in operation.
- Check that the actuator is correctly mounted before operating the device.
- Make sure that the connection bolts can withstand the wear and that they are safely secured before operating the device.
- Check that the actuator can move freely throughout the whole working area before operating the device.
- Use the actuator only within the specified working limits.
- Check that the actuator is connected to a power supply with the correct voltage and current source before operating the device.
- Switch off the main power supply when the actuator is not in use to prevent unintentional operation.
- Do not exert force on the side of the actuator.
- Make sure that the cable cannot be pressed upon, pulled or subjected to any other stress.
- Never unplug any cables or connectors during operation or with power on.
- Stop using the actuator immediately if it seems faulty or broken.
- Never try to open the actuator, as that will compromise the sealing and the proper functioning of the device.
- Do not kick or step on the actuator.
- Check the actuator and joints for extraordinary wear periodically.
- Keep out of reach of children.
03. Warranty

All REGNER® products have a warranty against manufacturing defects. The warranty period begins on the purchase date of the product. The seller is responsible for nonconformities that become apparent within the time stipulated by the applicable law.

03.01. Warranty Exclusions

REGNER® is entitled to deny any warranty if:

- The actuator has not been used correctly or its usage specifications (load, temperature, duty cycle, voltage, current, etc.) have not been respected.
- The actuator has not been maintained correctly.
- The actuator has been manipulated.
- The actuator has been exposed to violent or abrasive treatment.

Nonconformities due to reasonable wear and tear of the actuator over time (such as faded paint) are excluded from warranty.

REGNER® reserves the right to request the return of all allegedly defective products for testing and verification.

Any additional warranty obligations for parts replaced free of charge or for any service provided without charge under this warranty shall be excluded. The warranty period for parts replaced under warranty will end on the expiry date of the warranty period of the main product.
04. Specifications

04.01. Label

RA47X.1000.50.290.300.D12
Batch No.: 20180424
Power supply: 12 V
Duty cycle: Max. 10 %
Max. current: 13 A
Max. load: 1000 N

WARNING
Improper use may cause damage or injury. Only to be opened by authorized personnel.

01. RA47X.1000.50.290.300.D12
- RA47X: actuator type
- 1000: max. load (N)
- 50: stroke length (mm)
- 290: retracted length, center to center (mm)
- 300: cable length (mm)
- D: rod end (D = standard / H = clevis)
- 12: mounting hole diameter (mm)

02. Actuator specifications
Basic specifications and actuator features.

03. Batch No.: XXXXXX
Identification number assigned to a particular lot of products that enables REGNER® to control their quality and trace their constituent parts.

04. Symbols

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Norms</th>
</tr>
</thead>
<tbody>
<tr>
<td>🚧</td>
<td>WEEE Directive 2002/96/EC</td>
</tr>
<tr>
<td>◆</td>
<td>Compliance to all relevant CE directives</td>
</tr>
<tr>
<td>📚</td>
<td>Please, check the user manual.</td>
</tr>
<tr>
<td>💡</td>
<td>Protection against electric shock, Class II appliance</td>
</tr>
</tbody>
</table>

04.02. Components

1. Rod end
2. Rod
3. Nut
4. Spindle
5. Housing
6. Seal
7. Cable
8. Connector (MOLEX 39-01-2066)
9. Mounting hole
# 04.03. Specifications

## General Specifications

<table>
<thead>
<tr>
<th>Specification</th>
<th>Specification Value</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Stroke</strong></td>
<td>50 mm</td>
</tr>
<tr>
<td><strong>Max. load</strong></td>
<td>1,000 N at 2 mm/s</td>
</tr>
<tr>
<td><strong>Max. speed (no load)</strong></td>
<td>70 mm/s</td>
</tr>
<tr>
<td><strong>Power supply</strong></td>
<td>12 VDC</td>
</tr>
<tr>
<td><strong>Max. current</strong></td>
<td>13 A</td>
</tr>
<tr>
<td><strong>Starting current</strong></td>
<td>15 A</td>
</tr>
<tr>
<td><strong>Integrated limit switch</strong></td>
<td>At stroke end points</td>
</tr>
<tr>
<td><strong>Connector</strong></td>
<td>Molex 39-01-2066</td>
</tr>
<tr>
<td><strong>IP rating</strong></td>
<td>IP65</td>
</tr>
<tr>
<td><strong>Retracted length (center to center)</strong></td>
<td>240.5 mm + stroke</td>
</tr>
<tr>
<td><strong>Weight</strong></td>
<td>1,500 g</td>
</tr>
<tr>
<td><strong>Housing material</strong></td>
<td>Aluminum</td>
</tr>
<tr>
<td><strong>Rod material</strong></td>
<td>Polished stainless steel</td>
</tr>
<tr>
<td><strong>Color</strong></td>
<td>Anodized silver</td>
</tr>
<tr>
<td><strong>Mounting holes Ø</strong></td>
<td>12 mm</td>
</tr>
<tr>
<td><strong>Cable length</strong></td>
<td>300 mm</td>
</tr>
<tr>
<td><strong>Operating temp.</strong></td>
<td>-20 °C to +60 °C</td>
</tr>
<tr>
<td><strong>Storage temp.</strong></td>
<td>-30 °C to +70 °C</td>
</tr>
<tr>
<td><strong>Duty cycle</strong></td>
<td>10 % (2 out of 20 min.)</td>
</tr>
<tr>
<td><strong>Lead</strong></td>
<td>5 mm</td>
</tr>
</tbody>
</table>

## Hall Sensor Specifications

<table>
<thead>
<tr>
<th>Specification</th>
<th>Specification Value</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Power supply</strong></td>
<td>4.5 - 5.5 VDC ± 3 %</td>
</tr>
<tr>
<td><strong>Current consumption</strong></td>
<td>&lt; 30 mA</td>
</tr>
<tr>
<td><strong>Max. output current</strong></td>
<td>4 mA</td>
</tr>
<tr>
<td><strong>Control signal levels</strong></td>
<td>&lt; 0.4 VDC (low), &gt; 4.5 VDC (high)</td>
</tr>
<tr>
<td><strong>Max. frequency (no load)</strong></td>
<td>3,040 KHz</td>
</tr>
<tr>
<td><strong>Phase shift, channel A to B</strong></td>
<td>90 ° ± 45°</td>
</tr>
<tr>
<td><strong>Rise/fall time (CLOAD = 20 pF)</strong></td>
<td>10 ns / 100 ns</td>
</tr>
<tr>
<td><strong>Pulses per revolution (PPR)</strong></td>
<td>32</td>
</tr>
<tr>
<td><strong>Resolution</strong></td>
<td>24 µm / pulse</td>
</tr>
</tbody>
</table>

### Output signal

- **Channel A**
  - T
  - High
  - Low
- **Channel B**
  - 90°
  - Direction
  - High
  - Low
04.04. Force Curves

Use in the dashed area is not recommended.
The above values are with a room temperature of 20 °C.

04.05. Electronic Limit Switches (ELS)

When the actuator reaches its fully extended or fully retracted positions, an electronic limit switch automatically cuts off the current to prevent damage to the motor. When it reaches either stroke end point, the actuator can move only in the opposite direction, until it is separated from the limit and it can resume its normal function and move freely in either direction.

04.06. Dimensions

All measurements are in mm.
05. Installation

05.01. Mechanical Installation

To install a REGNER® actuator, simply slip a pin through the hole on each end. Mounting pins must be parallel to each other to keep the actuator from bending and being damaged.

The actuator should be installed so that the force of the load is exerted on the center of the rod. Excessive off-center loads may cause bending and lead to premature failure.

To prevent premature wear, make sure that the mounting pins are fixed at both ends, are solid, and do not have excessive free play. However, the actuator must be able to rotate around the pivot point of the rod, as this will allow the actuator to move freely along the full stroke length, both in the development phase and during normal operation. Examine the area around the housing and see that no components can get trapped and damage the application and the actuator.

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**CAUTION!**
- Mounting pins must have the correct dimensions and limited free play.
- Any bolts and nuts used for the installation must be made of high-quality steel.
- Do not apply an excessive torque on the mounting bolts to avoid stressing the fixtures.

**WARNING!**
If the actuator is used in an application that may cause personal injury, it is the responsibility of the application manufacturer to introduce the necessary safety measures to prevent personal injury in case of failure.

**WARNING!**
REGNER® actuators are not designed to be used in the following applications: aircraft, explosive environments, nuclear power generators, and offshore installations.
05.02. Electrical Installation

• Voltage must be switched off when the rod reaches the ends of the stroke or if an excessive load occurs mid-stroke to prevent damage to the actuator.
• Make sure that the switch can handle the maximum motor current.
• ELS will automatically switch off the actuator when the rod reaches the ends of the stroke or if an excessive load occurs mid-stroke.

1. Power
2. Position control

1. Motor -
5. Motor +

Molex 39-01-2066

CAUTION!

• Make sure the leads and cables leading to the motor can handle the maximum motor current.
• For additional protection, use a fuse between the actuator and the power source.
• Do not work on the actuator or the wiring with the power switched on!

Hall sensor

• The Hall sensor may operate with voltages of 4.5 - 5.5 VDC ± 3 %. Do not use a different voltage.
• Standard output: 0.4 - 4.5 VDC, square waves.

Wire cross-sections

To avoid malfunctions due to voltage drops, the cross-section of the wires connecting the actuator and the power supply must have an appropriate diameter.

06. Maintenance

The actuator is a closed unit and does not require internal maintenance. In fact, the actuator is not to be opened by unauthorized personnel. However, some external maintenance must be performed on a regular basis:

• Clean the actuator with a dry cloth to remove dust and dirt.
• Inspect the actuator for mechanical damage or wear.
• Inspect the actuator’s attachment points, cables, rod ends, housing, and connector, and check that the device works correctly.
## 07. Troubleshooting

<table>
<thead>
<tr>
<th>Symptom</th>
<th>Possible cause</th>
<th>Action</th>
</tr>
</thead>
<tbody>
<tr>
<td>The motor produces no sounds or the rod does not move.</td>
<td>1. Actuator not properly connected to the power supply.</td>
<td>A. Check the connection to the power supply or the control unit, if any.</td>
</tr>
<tr>
<td></td>
<td>2. Burned fuse.</td>
<td>B. Please contact REGNER®.</td>
</tr>
<tr>
<td></td>
<td>3. Damaged cable.</td>
<td></td>
</tr>
<tr>
<td>Excessive electricity consumption.</td>
<td>1. Misaligned or excessive load.</td>
<td>A. Align or reduce the load.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>B. Run the actuator with no load.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>C. Please contact REGNER®.</td>
</tr>
<tr>
<td>The motor runs but the spindle does not move.</td>
<td>1. Damaged gearing system or spindle.</td>
<td>A. Please contact REGNER®.</td>
</tr>
<tr>
<td>The actuator cannot lift a full load.</td>
<td>1. Misaligned or excessive load.</td>
<td>A. Wait for the overcurrent protection system to reset (5 minutes).</td>
</tr>
<tr>
<td></td>
<td>2. Insufficient power supply.</td>
<td>A. Align or reduce the load.</td>
</tr>
<tr>
<td></td>
<td>3. Current cut off due to excessive load.</td>
<td>B. Check the power supply.</td>
</tr>
<tr>
<td></td>
<td>4. Damaged motor.</td>
<td>C. Please contact REGNER®.</td>
</tr>
<tr>
<td>The motor runs too slowly, does not run with full force or runs in smaller steps.</td>
<td>1. Excessive load.</td>
<td>A. Wait for the overcurrent protection system to reset (5 minutes).</td>
</tr>
<tr>
<td></td>
<td>2. Voltage drop in the cable (long cables may affect performance).</td>
<td>B. Reduce the load.</td>
</tr>
<tr>
<td></td>
<td>3. Current cut off due to excessive load.</td>
<td>C. Check the power supply.</td>
</tr>
</tbody>
</table>

### The actuator cannot hold the load.

1. Excessive load.

A. Reduce the load.

### There is no feedback from the Hall sensor.

1. Actuator not properly connected to the power supply.

A. Check the connection to the power supply or the control unit, if any.

B. Please contact REGNER®.

### The output signal from the Hall sensor is out of range.

1. Incorrect power supply.

A. Check and correct the power supply.

B. Please contact REGNER®.

## 08. Application Policy

REGNER® products can be used in a wide range of applications in health care, household or industrial equipment, for example. REGNER® cannot know and check all the conditions in which REGNER® products are installed and used. The suitability and functionality of a REGNER® product, as well as its performance in a variety of conditions, can only be verified by testing, and it shall ultimately be the responsibility of the customer using a REGNER® product.

REGNER® is solely responsible that REGNER® products comply with the established specifications, whereas it remains the responsibility of the customer to ensure that a specific REGNER® product can be used for a specific application.

## 09. Contact

For technical assistance, please contact the REGNER® Technical Department at info@regner.es.